

maXYmos BL

XY monitor for good/bad evaluation of curves

maXYmos BL monitors and evaluates XY curves in which two measured variables must be in a certain relationship to each other.

The quality of an individual production step, an assembly or the entire product can be determined based on the shape of such measurement curves. An early decision on good or bad parts not only means savings in time and costs for downstream processes, but also prevents customer errors, including the resulting damage, service cases and costs for analyses.

Description

In addition to a modern and practical housing design, the monitor impresses with its clear menu navigation and practical functionality. The high-contrast colour touchscreen allows maXYmos BL to be operated quickly and easily and process information to be displayed clearly.

The menus are designed in such a way that only the information required for the respective function is displayed.

maXYmos BL is available in various versions and is scalable in terms of both hardware and software. The device provides the relevant functions with which most standard tasks in the field of XY monitoring can be solved.

Application examples

- Pressing in ball bearings
- Rotating and swivelling seat backrests
- · Riveting and caulking of housing parts
- Tactile operations on rotary switches etc

During press-fitting, the typical measurement curves are recorded using force and displacement sensors, while torque and angle of rotation sensors are used for swivelling processes. With maXYmos BL, all measured variables that can be measured with piezoelectric, strain gauges, potentiometers or sensors with ±10V signal output can be recorded, visualised in relation to each other and monitored.

Typ 5867C



Standard scope*

- Measurement function Y(X), Y(t), Y(X,t) or X(t)
- Evaluation via UNI-BOX, LINE-X, LINE-Y, ENVELOPE, NO-PASS (real-time threshold)*
- 4 evaluation elements per curve
- Up to 8,000 XY value pairs per curve
- Short evaluation time, up to 10 parts/second
- 16 measurement programs
- Ethernet TCP/IP for web UI and data transfer
- EtherNet/IP, EtherCAT, PROFINET for process values and control*
- Dig. IO (24 V) for control and results
- 2 real-time switching signals for X and Y threshold*
- Sensor X: ±10 V, potentiometer, or incremental*
- Sensor Y: Piezo or strain gauge and ±10 V*
- Front panel, table or wall mounting
- Info pages on the diagnosis of the cause of NIO
- Internal part ident generator selectable
- Warning and alarm messages
- Access protection for different user groups
- 5" colour touchscreen

Licensed functions*

- Connections and security (incl. LDAPS / AD)
- Extended evaluations (6 EO, GET-REF, CALC)
- IIoT connectivity via OPC-UA
- Sequencer mode
- * Functionality depends on hardware and licences.

Nominal measuring range

Measuring range overload

Maximum input voltage 2)

Linearity error

Input noise, typ,

1 Hz to 2 kHz

Offset drift

Gain drift



All the following information applies to $T_{operate}$ = +25 °C, U_{in} = 24 VDC, unless otherwise specified and cable length <30 m.

•	_	
Measuring channels		
Measuring channels	Quantity	1x channel > 1x channel \
Cut-off frequency -3dB (digital filters deactivated)	Hz	>2 000
Sampling rate X/Y, max.	Sps	5 000
Resolution per channel	Bit	24
Accuracy class after calibration (25 °C, rH <50 %, without operate jump)	%	0.3
Digital low-pass filter per channel	Hz	in steps 1 2 000, or Of
Channel X Potentiometer (X8) Potentiometer input		
Supply voltage	VDC	4.16 ±5 %
Short-circuit resistance 1)	VDC	4.16 ±3 //
Measuring range	%	0 10
Track resistance	kΩ	1 !
Wiper current @DC	μA	
Linearity error	% FS	<±0.0
Offset drift	ppm/°C	<±5
Gain drift	ppm/°C	<±5
Input noise, typ, 1 Hz to 2 kHz	ppm rms	4(
Connection technology	1	3-wir
Monitor output potentiometer		
Output voltage @ potentiometer setting 0 %	VDC	0.42 ±5 %
Output voltage @ potentiometer setting 100 %	VDC	4.58 ±5 %
Permissible load	kΩ	>1
Linearity error	% FS	<±0.02
Output noise, typ, 1 Hz to 2 kHz	uVrms	20
Channel X ±10 V voltage input (X8)	1	
Sensor supply	1.15.0	_
Supply voltage, nom. 3)	VDC	24
Supply current, max.	mA	20
Short-circuit resistance 1)		Ye
Measurement input		
Input resistance	kΩ	10
Internal source resistance, max.	Ω	5

Channel Y ±10 V voltage input (X9))	
Sensor supply		
Supply voltage, nom. 3)	VDC	24
Supply current, max.	mA	200
Short-circuit resistance 1)		Yes
Measurement input		
Input resistance	kΩ	100
Internal source resistance, max.	Ω	50
Nominal measuring range	V	±10
Measuring range overload	V	±11
Maximum input voltage 2)	V	±20
Linearity error	% FS	<±0.02
Offset drift	ppm/°C	<±30
Gain drift	ppm/°C	<±50
Input noise, typ, 1 Hz to 2 kHz	uVrms	100
Channel Y Piezo (X7) Number of channels		
Measuring range 1	pC	±100 ±750
Measuring range 2	pC	±750 ±7 500
Measuring range 3	pC	±7 500 ±75 000
Measuring range 4	pC	±75 000 ±750 000
Drift	1 1 -	
25 °C, rF < 50 % (non-condensing)	pC/s	<±0.05
50 °C, rF < 60 % (non-condensing)	pC/s	<±0.2
50 °C, rF < 70 % (non-condensing)	pC/s	<±0.2
Input noise, typ, 1 Hz to 2 kHz		
Measuring range 750 pC	pCrms	0.1
Measuring range 7 500 pC	pCrms	0.16
Measuring range 75 000 pC	pCrms	10
Measuring range 750 000 pC	pCrms	16
Reset-Operate jump	рC	<±2
Gain drift	ppm/°C	<±100
Linearity error		
Measuring range 750 pC	%FS	<±0.02
Measuring range 7 500 pC	%FS	<±0.02
Measuring range 75 000 pC	%FS	<±0.02
Measuring range 750 000 pC	%FS	<±0.02
Switchover times		
Reset → Operate	Pa 5	<2.5
Operate → Reset	ms	<2.5
(drop to <0.3 %)		

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% FS

ppm/°C

ppm/°C

 uVrms

±10

±11

±20

<±0,02

<±30

<±50

100



Channel Y Strain gauge (X6)			Measuring prog
Supply, unloaded	VDC	5 ±5 %	Quantity
Supply at 200 Ω load	VDC	4.9 ±5 %	Switching via
Short-circuit resistant 1)		Yes	Switching time
Permissible bridge resistance	Ω	200 1 000	Switching thresl
Measuring range	mV / V	- 5 5	Quantity
Linearity error	%FS	<±0.1	Channel assign
Input noise, typ,	mV/V	0.005	Switching time
1 Hz to 2 kHz	rms	0.005	
Connection technology		4-wire / 6-wire	Output
			Mode
ncremental (X12)			Influence on v
Sensor supply 24 V			
Voltage nom. ³⁾	VDC	24	Device status LE
Maximum current	mA	450	
Short-circuit resistance 1)		Yes	D1 Device statu
Sensor supply 5 V			
Tension	VDC	5 ±5 %	Digital inputs ar
Maximum current	mA	300	Digital inputs
Short-circuit resistance 1)		Yes	Quantity
Incremental encoder input			Standard
Interfaces		al, symmetrical	Input voltage I
	(RS-422)		Input voltage I
		al, asymmetrical,	Input current,
	5V level		Input current,
		al, asymmetrical,	Response time
	 ' 	lector (1k pull-up)	
Internal digital resolution	Bit	32	Digital outputs
Max. Input frequency 4)			Quantity
ABZ signal, sym. (RS-422)	MHz	10	Туре
ABZ signal, asym., 5 V		5	Output voltage
ABZ signal, asym., open collector		0.8	Output voltage «0», @ RL = 2
			Output voltage
Cycle control	In:		«1», @ RL = 2
START-STOP	0	hreshold X / Y / Fieldbus /	Output curren
31AK1-31OF	Touchscree		Total output cu
	1.0000	···	Short-circuit re
Measuring functions			Response time
START-STOPP	Y	(X), Y(t), Y(X, t), X(t)	Sensor supply
Curve memory	XY pairs	Max. 8 000	Supply voltage
Historical curves	'	-1 1	Supply current
(for NIO diagnosis)		The last 320	Short-circuit re
<u> </u>	'		
Evaluation elements (EOs)			Real-time reacti
	UNI-BOX	/ LINE-X / LINE-Y /	Switching thre
EO types	EN	VELOPE / NO-PASS	EO type "NO-
Reference points in X direction	Absol	ute, Block, Trigger-Y	
Editing	Num	erical input, drawing	Data export
Evaluation time	ms	<50 (with 4 EOs)	Format

Measuring programmes			
Quantity		16	
Switching via	Men	u / DigIn / Feldbus	
Switching time	ms	<5	
Switching thresholds (real time	e)		
Quantity	2 (S1 and	2 (S1 and S2)	
Channel assignment	X or Y (sel	X or Y (selectable)	
Control to a store	Threshold	Threshold X reached,	
Switching time	threshold	Y reached	
Output	Dig. out o	Dig. out or fieldbus	
Mode	Free-runni	Free-running or latch	
Influence on valuation	No (specia	No (special case "NO-PASS")	

.ED

	Orange	Start up
D1 Device status	Green	Ready for operation
	Red	Error
Digital inputs and outputs (X2)		
Digital inputs		
Quantity		11
Standard		DIN EN61131-2
Input voltage level state "0"	V	-3 5
Input voltage level state "1"	V	15 30
Input current, Uin = 30 V	mA	<5
Input current, Uin = 5 V	mA	<0.8
Response time, internally	us	<100

Quantity		11
Туре		High-side switch
Output voltage, nom ⁻³⁾	VDC	24
Output voltage, typ., state «0», @ RL = 220 Ω	mVDC	1
Output voltage, typ., state «1», @ RL = 220 Ω	VDC	23.5
Output current per output	mA	100
Total output current	mA	400
Short-circuit resistant 1)		Yes
Response time	us	<100
Sensor supply		
Supply voltage, nom. 3)	VDC	24
Supply current, max.	mA	400
Short-circuit resistance 1)		Yes

ions

Switching thresholds \$1/\$2	ms	<1
EO type "NO-PASS"	ms	<1

Format	CSV
Target	Server
Transmission via	Ethernet

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Ethernet interface (X3)		
Data rate	MBit	1000
Fieldbus (X10, X11)		
Protocols	EtherCAT, PROFINET, Ethernet/IP	
USB interface (X13)		
Interface	USB 2.0 F	ull Speed, Type A
Supply voltage	VDC	5 ±5 %
Output current max.	mA	500
Power supply (X1) Supply voltage	VDC	18 30 (typ. 24)
Power consumption typ.	VDC	10 50 (typ. 24)
(24 VDC, without peripherals)		
5867Cx0x, 5867Cx1x (with display)		5.5
5867Cx2x (without display)		3.8
Galvanic isolation		Functional separation
Feldbus Status LEDs ⁴⁾		
PROFINET	D2/SF	Red: System error
I IVOI IINET	D3/BF	Red: Bus error
EtherCAT	D2/RUN	Green: Run
LuieiCAI	D3/ERR	Red: Error
EtherNet/IP	D2/MS	Network status
LUIGHNEU/IF	D3/NS	Netzwerk Status

General technical data		
Protection class (IEC 60529)front panel mountingdesktop housing	IP	60 20
Operating temperature range	°C	0 50
Service temperature range	°C	0 50
Storage temperature range	°C	-10 60
Rel. humidity (non-condensing))	%	10 90
Dimensions		See drawings
Weight		
5867Cx0x		800
5867Cx1x	g	850
5867Cx2x		850

EMV	
	EN 61326-1 :2013
	(Product standard - Equipment
Standards	for measurement and control
	technology, laboratory, class A,
	industry)

Legend

- ¹⁾ Short-circuit resistance means: No damage in the event of a permanent short circuit; short circuit always against reference potential; reboot of device is permitted
- ²⁾ Higher input voltages can destroy electronics.
- $^{\scriptscriptstyle 3)}$ Output voltage is supply voltage minus small internal voltage losses (up to 2 V).
- $^{\mbox{\tiny 4})}$ For cable lengths <5 m. The maximum input frequency decreases with longer cable lengths.
- ⁵⁾ Basically according to the standards of the fieldbus protocols.



Connections

The actual connections available depend on the design of the appliance. The "Application" chapter contains further information on the correct use of the connections.

X1 Power supply

Pinout	Function	Pin
₽	24 VDC	1
	GND	2
	Shield (housing)	3

X3 Ethernet

Pinout	Function	Pin
	RX +	1
	RX –	2
	TX +	3
	-	4
	-	5
	TX –	6
	-	7
	-	8

X10/X11 Industrial Ethernet

Pinout	Function (per plug)	Pin
	RX +	1
X10 IN X11 OUT Industrial Ethernet	RX –	2
	TX +	3
	-	4
	-	5
	TX –	6
	-	7
	-	8

X13 USB type A

Pinout	Function	Pin
USB A	5 V	1
	D-	2
	D+	3
	GND	4

X8 Channel X

Pinout	Function	Pin
	24 V sensor supply	1
	nc	2
	Monitor output potentiometer	3
	Input ±10 V signal	4
	Power supply potentiometer –	5
(o o	Power supply potentiometer +	6
	nc	7
000	Potentiometer tap input	8
	GND (sensor supply)	9
(° ° ° °)	nc	10
	GNDX	11
	nc	12
	nc	13
	GNDX	14
	nc	15

Note: nc = not connected

X6 Channel Y (DMS)

Pinout	Function	Pin
	Supply +	1
	Signal +	2
	Sense cable –	3
0 0 0	GNDY	4
	nc	5
	Sense cable +	6
	Signal –	7
	Supply –	8
	nc	9

Note: nc = not connected

X9 Channel Y (±10V voltage)

Pinout	Function	Pin
	nc	1
	Input ±10 V signal	2
	GND (sensor supply)	3
	nc	4
	24V sensor supply	5
	nc	6
	GNDY	7
	nc	8
	nc	9

Note: nc = not connected

X7 Channel Y (Piezo)

Pinout	Function	Pin
1	Charge input	1
2	GNDY	2

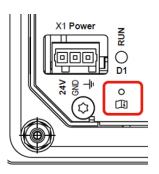


X2 Digital I/O

Pinout	Function	Pin
	DO 1	1
	DO 2	2
	DO 3	3
	DO 4	4
	DO 5	5
	DO 6	6
	DO 7	7
	DO 8	8
	DO 9	9
	DO 10	10
	DO 11	11
11 ^ 11	24 V sensor supply	12
0 0	GND DO / sensor supply	13
	DI 1	14
	DI 2	15
	DI 3	16
	DI 4	17
	DI 5	18
	DI 6	19
رت	DI 7	20
	DI 8	21
	DI 9	22
	DI 10	23
	DI 11	24
	GND DI	25

Factory reset button

Pressing the factory reset button for more than 10 seconds resets the device to the factory settings.



X12 Incremental

Pinout	Function	ABZ Sym	ABZ Asym	Pin
	24 V sensor supply			1
	5 V sensor supply			2
	GNDY Signal Torque			
	Internally connected			3
	to X9 pin 7			
	Input ±10 V Torque			
	Internally connected			4
	to X9 pin 2			
(°°°)	Track A / clock signal +	A+	А	5
	Track B / Data Signal +	B+	В	6
	nc			7
0 0	Z gauge signal +	Z+	Z	8
	GND			9
	GND			10
	GNDY Signal Torque			
	Internally connected			11
	to X9 pin 7			
	Track A / clock signal –	A-		12
	Track B / Data Signal –	В-		13
	GND signal track			14
	Z gauge signal –	Z-		15

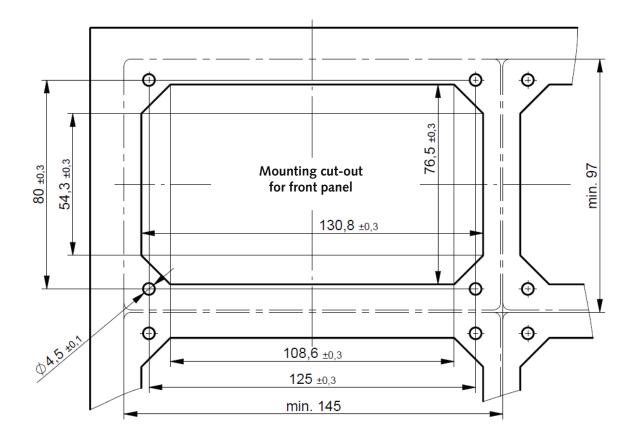
Note: nc = not connected

Note: To connect the torque sensor 4502A to X12, please use the cable 18027071. To connect the torque sensor 4503B to X12, please use the cable 18026961.



Installation

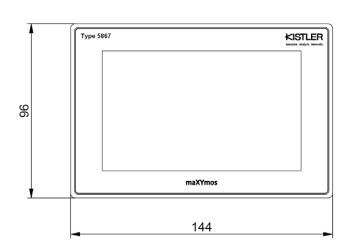
Mounting cut-out for front panel mounting:

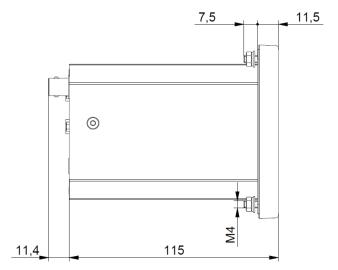




Dimensions

Illustration shows 5867C001:





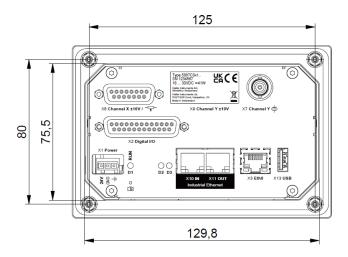
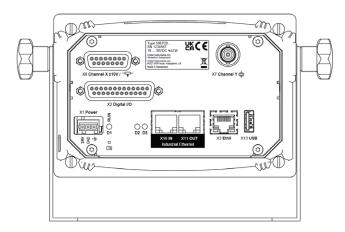
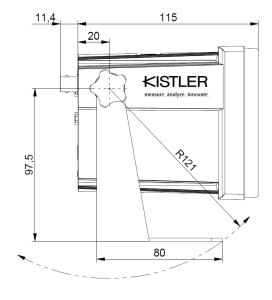
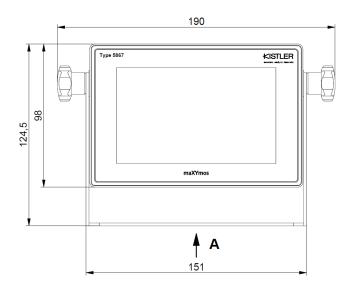


Illustration shows 5867C011:







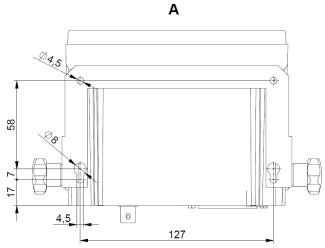
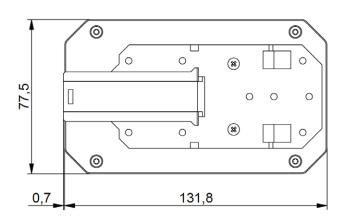
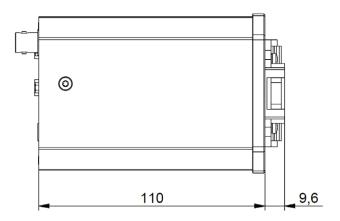


Illustration shows 5867C02x:

5867C_003-704e-02.25



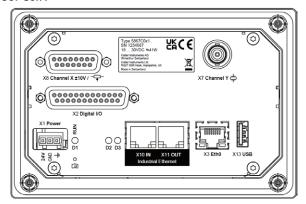


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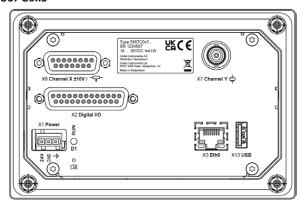


Connections

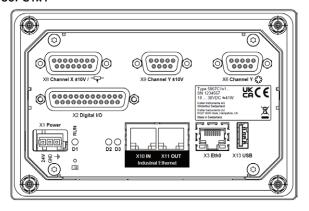
5867C0x1



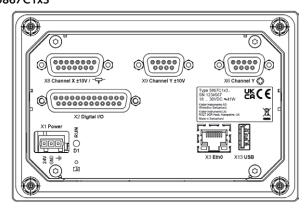
5867C0x3



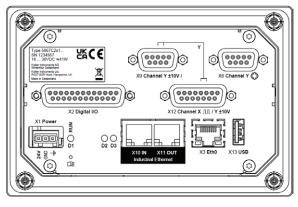
5867C1x1



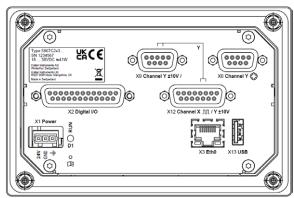
5867C1x3



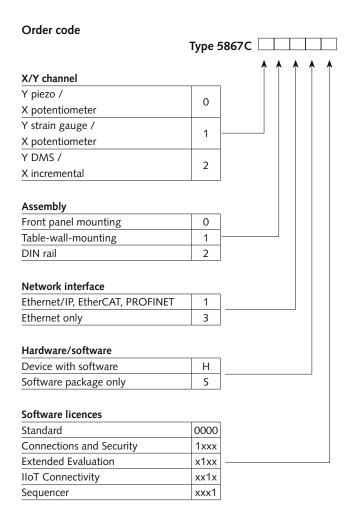
5867C2x1



5867C2x3







Accessories supplied	Туре
 Plug set, strain gauge version, 	5867AZ010
complete for sensors, dig.IO	
and power supply	
 Plug set, piezo version, 	5867AZ011
complete for sensors, dig.IO	
and power supply	

Accessories (optional) Type • Desktop/wall-mounted housing 5867AZ000 • Power supply unit 5781B5 90 - 264 VAC / 24 VDC ready for connection max. 90 W (3.75 A), country cable configurable · Adapter cable for routing 1200B156AX a potentiometric X= Number displacement or of devices; angle signal max. 8 to several maXYmos • Ethernet cable RJ45 1200A49 5.0m crossed

• Ethernet cable RJ45

0.5m crossed blue

Content	Note	BL
User Groups	Individual user groups with configurable access rights	
User and Password options	Password reuse prevention, lock user, password expiration	0
LDAP user management	Centralized user access management with LDAP/LDAPS/AD	
6 EOs	Allows two more EOs (+2) in each Measurement Program	
EO Colo	O Calc allows simple mathematical Operation (+, -, *, /) with two operands,	
EO Caic	including UVT table access	
EO Get-Ref	EO Get-Ref covers more options to get reference values for evaluation or Calc	701
EO Envelope extensions	Adds extended functions, trend tracking warning, catch zone Y	
Re-Entry ignore (for all EO)	If active, an EO will become inactive after the first contact with the signal (ok or nok)	
ODC IIA Convor	OPC-UA Data Access for Setup Parameters and	
IIoT Connectivity OPC-UA Server	OPC-UA Events for cyclic reports	
Sequencer Mode	General sequencer for internal state machine / soft PLC	
Part-ID from Barcode/USB	Barcode reader may write ID when connected via USB	
	User Groups User and Password options LDAP user management 6 EOs EO Calc EO Get-Ref EO Envelope extensions Re-Entry ignore (for all EO) OPC-UA Server Sequencer Mode	User Groups Individual user groups with configurable access rights User and Password options Password reuse prevention, lock user, password expiration LDAP user management Centralized user access management with LDAP/LDAPS/AD 6 EOs Allows two more EOs (+2) in each Measurement Program EO Calc allows simple mathematical Operation (+, -, *, /) with two operands, including UVT table access EO Get-Ref EO Get-Ref covers more options to get reference values for evaluation or Calc EO Envelope extensions Adds extended functions, trend tracking warning, catch zone Y Re-Entry ignore (for all EO) If active, an EO will become inactive after the first contact with the signal (ok or nok) OPC-UA Server OPC-UA Data Access for Setup Parameters and OPC-UA Events for cyclic reports Sequencer Mode General sequencer for internal state machine / soft PLC

1200A49A3



Block diagram

Complete device

