KISTLER measure, analyze, innovate.

WIM Data Logger

for dynamic vehicle weighing with Lineas sensors

The WIM data logger Type 5204AC... in combination with Lineas Weigh In Motion (WIM) sensors enable customers to monitor traffic and gather accurate vehicle data.

- High weighing accuracy (OIML R134 certified) 1)
- Able to monitor up to 4 traffic lanes
- Handling of stop & go traffic
- Wide speed range (0 ... 250 km/h)
- Measuring range up to 50 tons axle load
- · Compact design with integrated amplifier
- Detect single or dual tires
- · Quick set up thanks to modern web interface
- Multiple languages available
- Vehicle classification
- · Flat tire detection

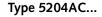
Description

The WIM data logger is a data processing unit specifically designed to interface with Lineas and Lineas Compact WIM sensors. It allows customers to monitor traffic in real time and to gather vehicle data.

The key is enhanced conditioning and processing of the Lineas and Lineas Compact WIM sensor signals to achieve the best weighing accuracy from low to high speed with the highest reliability. The WIM data logger can be easily integrated into the overall system by the system integrator, providing a customized solution according to the needs of the end user.

Both WIM sensors, Lineas and Lineas Compact, can be directly connected to the WIM Data Logger. Additionally, there are various digital inputs and outputs to interface peripheral devices such as loop cards, beam arrays, traffic signals, camera triggers, barriers, etc. The WIM data logger is available in versions with 4 or 8 channels to monitor 1, 2, 3 or 4 traffic lanes (3 and 4 lanes, only staggered layout).

In Kistler KiTraffic Plus systems, multiple WIM Data Loggers can be combined to monitor a virtually unlimited number of lanes with one single interface to the end user. Every lane can be equipped with 2 to 8 WIM sensors.





Technical Data

General Data

| Measuring range (axle load) | | tons | 0 50 |
|---------------------------------|---------|------|------------|
| Speed range (without stop & go) | | km/h | 3 250 |
| Speed range (stop & go) | | km/h | 0 250 |
| Operating temperature range | | °C | -20 65 |
| Degree of protection | EN60529 | | IP61 |
| Mounting | EN50045 | Туре | TS-35 |
| | | | (DIN Rail) |
| Dimensions | WxHxD | mm | 213x77x136 |
| Weight (4/8 channels) | | kg | 1,5/1,65 |
| Vehicle classification | | | FHWA-13 |
| | | | EUR-13 |
| | | | RUS-12 |

Electrical Data

| Supply voltage | | VDC | 18 30 |
|---------------------------------|-------|-----|-------|
| Current consumption (typically) | @18 V | mA | 210 |
| | @24 V | mA | 150 |
| | @30 V | mA | 120 |

Conforming to CE and EMC standards

Sensor Inputs

| Number of channels | | 4 or 8 |
|---------------------------|------|--------|
| Lineas WIM sensor | Туре | 9195GC |
| Lineas Compact WIM sensor | Туре | 9196AC |

Other Interfaces

| Communication ports Ethernet (TCP/IP) | | 2 |
|---|----|----------|
| Digital input channels | | 4 |
| Type: Optocoupler with current limitation | | |
| Minimal high-level input current | mA | 2,5 |
| Differential voltage range (between +/-) | V | 0 30 |
| Digital output channels | | 4 |
| Type: Semiconductor relais | mA | max. 120 |
| Differential voltage range (between +/-) | V | -30 30 |
| Display interface Type RS-485 | | 1 |
| | | |

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System accuracy and speed range depend on sensor layout and road quality. Detailed system information and OIML certificates are available on www.kistler.com/wim



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Applications

Due to the high measuring accuracy over a wide speed range and the ability to interface different external devices the WIM data logger can be used for several applications:

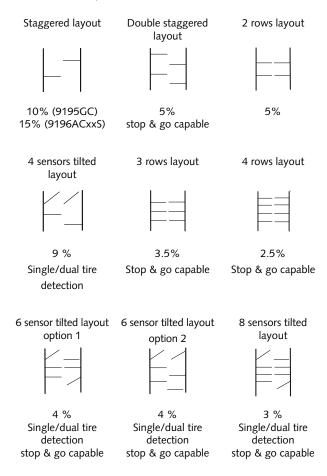
- Traffic data collection (e.g. statistics, count & classify)
- Weight enforcement (preselection or direct enforcement of overloaded vehicles)
- Toll collection (manual or automatic toll-by-weight)
- Industrial truck weighing (weight monitoring at harbors, mining, concrete plants or other industrial facilities)
- Overload detection for bridge protection

Typical Layouts

With KiTraffic Plus, each layout can be installed on a virtually unlimited number of lanes.

Layout for one lane:

Typical GVW accuracies for Lineas Type 9195GC (if not mentioned otherwise)





Induction loops/beam array not considered in layouts Both driving directions possible

This information corresponds to the current state of knowledge. Kistler reserves the right to make technical changes. Liability for consequential damage resulting from the use of Kistler products is excluded.

Communication

The control unit (user interface) is usually a computer located in a remote office which is connected to the WIM data logger via Ethernet cable or wireless router. There are two options to communicate with the WIM data logger.

- 1 Via the Kistler web interface (by using a common web browser)
- 2 Via a machine readable interface
- **1** The web interface of the Kistler WIM data logger allows the following tasks to be performed:
 - System setup (configuration and calibration)
 - Visualization of vehicle data (live and history)
 - Supervision (detect violations)
 - Access system information and status
 - Remote support
 - **–** ...

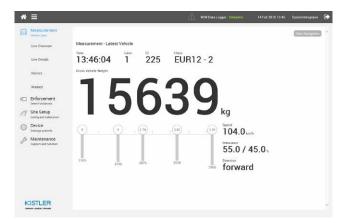


Fig. 1: Kistler web interface

2 The machine readable interface is based on a state of the art RESTful API interface. This allows quick and easy data communication and device control of any server in the network with the WIM data logger.

Output Data

The WIM data logger generates a large variety of vehicle data such as:

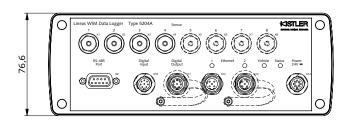
- Gross vehicle weight
- Axle information (wheel and axle load, axle distance, number of axles, wheel with single tire or dual tires)
- Vehicle speed and length
- Driving direction
- Imbalance (difference left/right in %)
- Time between vehicles (traffic density)
- Violations
- · Driving behavior
- Vehicle classification
- Flat tire information

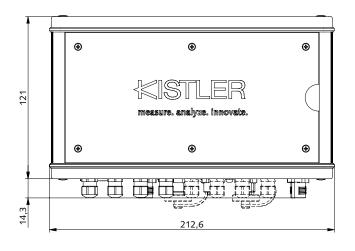
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Mounting and Dimensions

The WIM data logger is typically mounted in a road side cabinet close to the WIM site. Inside this electrical cabinet, it can be fixed to a DIN rail with the provided adapter in three different positions.





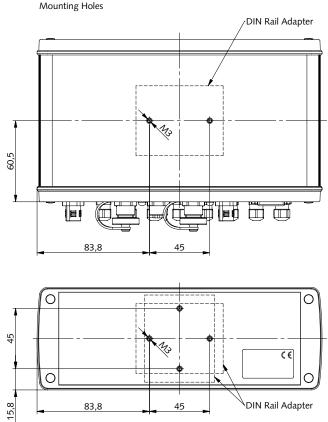


Fig. 2: Mounting and dimensions of Type 5204A...



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| Included Accessories | Ordering No. |
|--|--|
| Cable for power supply | 1700A119A2 |
| (M12 – open end, l = 2 m) | |
| • Ethernet cable (M12 – RJ-45, l = 2 m) | 1200A195A2 |
| Digital input cable (M12 – open end, | 1700A115A2 |
| l = 2 m) | |
| DIN rail adapter | 55126892 |
| Protection cap for D-Sub | 55066918 |
| Protection caps for M12 (fix mounted) | 65008419 |
| Sealing inserts for not used channels | 55138567 |
| Systems including WIM data logger: | |
| KiTraffic Plus | 9843A |
| KiTraffic Statistics | 9841A |
| Weigh In Motion System | 9835A |
| | |
| Optional Accessories | Ordering No. |
| 14044 | == 4 40 400 |
| WIM system components with loop card | 55140423 |
| prewired on a DIN rail | |
| prewired on a DIN rail • WIM system components for beam array | 55140423 55140424 |
| prewired on a DIN railWIM system components for beam array prewired on a DIN rail | 55140424 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * | 55140424 9835AZ100 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * Loop card for up to 4 inductive loops | 55140424 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * Loop card for up to 4 inductive loops (for >10 km/h) | 55140424 9835AZ100 9835AZ200 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * Loop card for up to 4 inductive loops (for >10 km/h) Beam array set for vehicle separation | 55140424 9835AZ100 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * Loop card for up to 4 inductive loops (for >10 km/h) Beam array set for vehicle separation incl. heating (for <20 km/h) for 1 lane | 55140424 9835AZ100 9835AZ200 9835AZ300 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * Loop card for up to 4 inductive loops (for >10 km/h) Beam array set for vehicle separation incl. heating (for <20 km/h) for 1 lane GPRS modem with antenna | 55140424 9835AZ100 9835AZ200 9835AZ300 9835AZ400 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * Loop card for up to 4 inductive loops (for >10 km/h) Beam array set for vehicle separation incl. heating (for <20 km/h) for 1 lane GPRS modem with antenna Digital output cable (M12 – open end, | 55140424 9835AZ100 9835AZ200 9835AZ300 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * Loop card for up to 4 inductive loops (for >10 km/h) Beam array set for vehicle separation incl. heating (for <20 km/h) for 1 lane GPRS modem with antenna Digital output cable (M12 – open end, I = 2 m) | 55140424 9835AZ100 9835AZ200 9835AZ300 9835AZ400 1700A117A2 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * Loop card for up to 4 inductive loops (for >10 km/h) Beam array set for vehicle separation incl. heating (for <20 km/h) for 1 lane GPRS modem with antenna Digital output cable (M12 – open end, I = 2 m) Power transformator 110 V for | 55140424 9835AZ100 9835AZ200 9835AZ300 9835AZ400 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * Loop card for up to 4 inductive loops (for >10 km/h) Beam array set for vehicle separation incl. heating (for <20 km/h) for 1 lane GPRS modem with antenna Digital output cable (M12 – open end, l = 2 m) Power transformator 110 V for beam array heating prewired on a DIN rail | 55140424 9835AZ100 9835AZ200 9835AZ300 9835AZ400 1700A117A2 55140425 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * Loop card for up to 4 inductive loops (for >10 km/h) Beam array set for vehicle separation incl. heating (for <20 km/h) for 1 lane GPRS modem with antenna Digital output cable (M12 – open end, I = 2 m) Power transformator 110 V for beam array heating prewired on a DIN rail Power transformator 230 V for | 55140424 9835AZ100 9835AZ200 9835AZ300 9835AZ400 1700A117A2 |
| prewired on a DIN rail WIM system components for beam array prewired on a DIN rail Power supply (24 VDC/100 W) * Loop card for up to 4 inductive loops (for >10 km/h) Beam array set for vehicle separation incl. heating (for <20 km/h) for 1 lane GPRS modem with antenna Digital output cable (M12 – open end, l = 2 m) Power transformator 110 V for beam array heating prewired on a DIN rail | 55140424 9835AZ100 9835AZ200 9835AZ300 9835AZ400 1700A117A2 55140425 |

| * | For measuring equipment only – for beam array heating |
|---|---|
| | power transformator Type 55140425 or 55140426 to be used. |

| Ordering key | Туре | e 5204A |
|--------------------------------------|------|---------|
| Number of Channels* | | |
| 4 Channels for WIM Sensors | 04 |] |
| 8 Channels for WIM Sensors | 08 | |
| SW order for existing device | - | |
| Scope of Delivery | | |
| Hardware & Basic Software | Н |] |
| Software only (for existing devices) | S | |
| Automated Tire Screening | | _ |
| No | 0 | |
| Yes | 1 | |

*Examples:

5204AC08H0: 8 channel device without Automated Tire Screening functionality.

5204AC--S1: Automated Tire Screening functionality for an existing WIM Data Logger in the field.