

2-Component sensor Fz, Mz

-10 ... 10 kN and -25 ... 25 N·m

This installation-friendly, piezoelectric 2-component sensor is suitable for measuring push/pull force Fz and a torque Mz acting on the sensor axis. Its high resolution allows measurement of the slightest dynamic changes in large forces and torques at non-rotating shafts.

- · Very compact, ready to install sensor
- High rigidity and high natural frequency
- Flexible adaption with mounting threads in double flanges
- Centering seats for coaxial mounting and optimum introduction of torque
- · Center hole for shaft passage

Description

Pressure and shear sensitive quartz disks are integrated under high preload between a hollow preload screw and a nut designed as the sensor case. Because of the extremely high rigidity of the sensor elements, the components Fz and Mz are measured practically without change of stroke or angle. The force and torque-proportional charge signal is picked up by electrodes and fed via a shielded cable to the charge amplifier. The latter converts the charge signals into proportional output voltages, which can be recorded and evaluated.

Flanges with tapped holes in the top and bottom sides of the sensor allow simple mounting on a shaft or adapter flange. Centering seats on both sides permit a very accurate coaxial fitting and a centric bore allows shafts to be inserted.

The sensor is rust-resistant and splash-water-protected. Together with the connecting cable Type 1698AD2, the sensor achieves the degree of protection IP65.

It should be noted that the measuring ranges are reduced by combined and eccentric loads.



Type 9345B





Type 9345B

Application

- · Measuring feed force and torque when drilling, thread cutting etc.
- Monitoring of screw driving processes and testing threaded fasteners
- Testing springs (torsion)
- Measurements on small thrust bearings, friction clutches etc.
- Measuring starting torques, irregular motion and torsional vibration on small servo and stepping motors
- Testing rotary switches and screw caps

Technical Data

	Type	9345B
Fz	kN	-10 10
Mz	N∙m	− 25 25
Fz	kN	-12/12
Mz	N∙m	-30/30
ing		
Fz	kN	0 10
M_z	N⋅m	0 25
		0 –25
Fz	kN	0 1
Mz	N∙m	0 2.5
		0 –2.5
Fz	pC/N	≈–3.7
Mz	pC/N·m	≈–190
	Mz Fz Mz ing Fz Mz Fz Mz Fz	Fz kN Mz N·m Fz kN Mz N·m ing Fz kN M·m Fz kN Mz N·m Fz kN Mz N·m



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		Туре	9345B
Threshold F	z	N	<0.02
Ī	Mz	mN⋅m	<0.35
Linearity, F	z	%FSO	≤±0.3
all ranges	Mz	%FSO	≤±0.3
Hysteresis, F	z	%FSO	≤0.5
all ranges	Mz	%FSO	≤0.5
Max. bending momen	t		
M_x , M_y		N⋅m	14.3
$(M_z = 25 \text{ N} \cdot \text{m}; F_z =$	0)		
M _x , M _y		N⋅m	
$(M_z = 200 \text{ N} \cdot \text{m}, F_z =$	= 0)		
Shear force max.			
$F_{x,y}$		kN	0.1 ¹⁾
$(M_z = 25 \text{ N} \cdot \text{m}; F_z =$	0)		
Mz		kN	
$(M_z = 200 \text{ N} \cdot \text{m}; F_z =$	= 0)		
Crosstalk			
$M_z \rightarrow F_z$		N/N·m	≤±2
$M_b \rightarrow F_z$		N/N·m	≤±0.5
$F_{x,y} \rightarrow F_z$ (typical)		N/N	≤±0.02
$F_z \rightarrow M_z$		mN·m/N	≤±0.04
$M_b \rightarrow M_z$		N·m/N·m	≤±0.02
$F_{x,y} \rightarrow M_z$ (typical)	mN·m/N	≤±0.3	
Rigidity			
c_z (F_z)		kN/µm	≈1.7
cφ (M _z)		N·m/µrad	≈0.19
Natural frequency			
f _n (z)		kHz	>41
$f_n (M_z)$		kHz	>32
Operating temperature	e range	°C	-40 120
Temperature coefficier			
sensitivity			
F _z		%/°C	-0.02
Mz		%/°C	-0.01
 Capacitance			
C _{Fz}		pF	≈65
C _{Mz}		pF	≈340
Insulation resistance		Ω	>10 ¹³
at 23 °C			
Degree of protection		EN60529	IP65
(with cable connect	ed)		
Connector			V3 neg.
Case material		DIN	1.4542
Weight		g	267
Tightening torque M _A		N·m	4
S torque MA			Ι,

¹⁾ Force applied in the flange plane

Dimensions 2-Component Sensor Fz, Mz

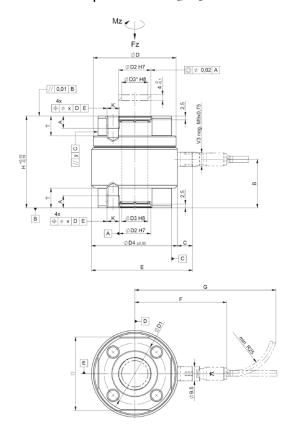


Fig. 1: Dimensions 2-component sensor F_z , M_z , Type 9345B

Dimensions in mm

Type	D	D1	D2	D3	D3*	D4		Н	A	
9345B	36	26	14	11	11	39	32	42	5	

Type	В	C	E	F	G	K	T	у	у
9345B	21,7	10	48,3	51	81	M5	9	0.15	0.35

^{*} Free passage with mounted centering rings



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Mounting

Mounting is accomplished using the flanges with tapped holes on both sides of the sensor. The contact surfaces to the sensor must be flat, rigid and clean. Centering seats and centering rings (included accessories) are provided to allow as accurate as possible coaxial fitting. Torque should be introduced with the smallest possible eccentricity (<0.02 mm) of the axes to be connected. Bending moments and shear forces must be avoided as far as possible.

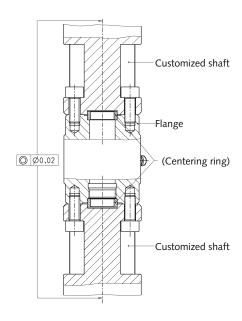


Fig. 2: Installation in shaft

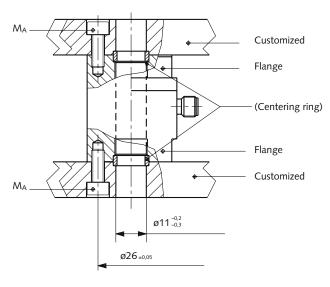
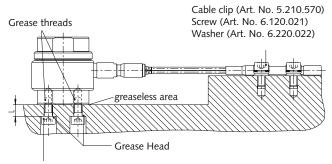


Fig. 3: Installation between base and cover plate

Installation

- The sensor is screwed onto a previously machined surface with four fixing screws. The mounting surface must not be painted or greased and the planeness of the contact surface must be within a tolerance of 5 microns.
- The connecting cable must be installed in such a way as to exclude any tangential, radial or axial forces to the sensor.
 The cable should be affixed as close as possible to the sensor on a suitable mounting surface.
- The tightening torque to be applied to each of the four fixing screws is 21 [N·m].



Type 9345B 4 pcs. Screw M5x12 (Art. No. 6.120.022) Tightening torques: M_{ν} [N·m]

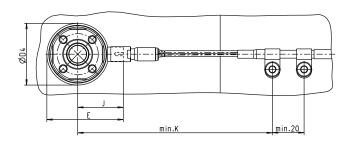


Fig. 4: Installation 2-component sensor Fz, Mz

Type	D4	E	J	K	L	M_{v}
9345B	39	48.3	28.8	130	7.3	4



Measuring System with 2-Component Force Link

2-Component Force Link with V3 neg. Connector	Degree of protection EN60529	Connecting Cable	Multichannel Charge Amplifier	Reading
Type 9345B		Type 1698AD2	Type 5073A211 Social Section (Section	Fz
V3 neg.	IP65	V3 pos. 2 x BNC pos.	Type 5015A F _z M _z	Mz

Included Accessories	Art. No.
• 2 x centering ring for Type 9345B	3.420.180
• 2x Cable clamp	5.210.570
• 2x screw	6.120.021
• 2x Flat washer	6.220.022

Optional Accessories

Type • Mounting flange for Type 9345B 9580A1 • Connecting cable 2-wire, 1698AD... V3 pos. $-2 \times BNC$ pos., L = 2 m or SP

• Connecting cable 2-wire, 1698AP...

V3 pos. – 2 x KIAG 10-32 pos., L = 2 m or SP

(see also data sheet for cables 1687B_000-545)

Ordering Key Type • 2-Component Sensor Fz, Mz 9345B

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